emesent FREEFLY ASTRO & ASTRO MAX SETUP GUIDE

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Using this manual

Hovermap is a powerful system that can be used as a LiDAR mapping payload, but also as an advanced autopilot for drones and other platforms. We therefore recommended that you read the user manual thoroughly to make use of all its capabilities in a safe and productive way.

Disclaimer and safety guidelines

This product is *not* a toy and must not be used by any person under the age of 18. It must be operated with caution, common sense, and in accordance with the instructions in the user manual. Failure to operate it in a safe and responsible manner could result in product loss or injury.

By using this product, you hereby agree that you are solely responsible for your own conduct while using it, and for any consequences thereof. You also agree to use this product only for purposes that are in accordance with all applicable laws, rules and regulations.

The use of Remotely Piloted Aircraft Systems (RPAS) may result in serious injury, death, or property damage if operated without proper training and due care. Before using an RPAS, you must ensure that you are suitably qualified, have received all necessary training, and read all relevant instructions, including the user manual. When using an RPAS, you must adopt safe practices and procedures at all times.

Warnings

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- Do not attempt to disassemble, repair, tamper with, or modify the this product. This product contains no user-serviceable parts inside. Any disassembly of the product enclosure will invalidate the IP65 rating and disrupt the factory calibration of LiDAR. Contact Emesent for any repairs or modifications.
- Always be aware of moving objects that may cause serious injury, such as spinning propellers or other components. *Never* approach a drone while the propellers are spinning or attempt to catch an airborne drone.



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This guide outlines how to prepare a Freefly Astro or Astro Max drone to carry the Hovermap ST or Hovermap ST-X. Once set up, the Hovermap and drone will be able to share autonomy command data and receive GPS through the electrical interface cable.

The key steps shown in this guide are:

- 1. Mount the Hovermap to the Freefly Astro
- 2. Install Emesent Commander on the Freefly Pilot Pro controller
- 3. Setup Hovermap and Freefly Astro for basic operations

1. **Pre-flight checklist**

- Hovermap is running the latest release of Cortex and Commander, or a minimum of Cortex version 3.4.
- Freefly Pilot Pro controller is fully charged.
- Freefly Astro/Astro Max batteries are fully charged.
- Freefly Astro/Astro Max parameters are set for Hovermap (section 2 below).

2. Set Astro/Astro Max parameters

If your Astro/Astro Max has firmware 1.6.14 or later installed, the following Astro parameters need to be set for it to operate with Hovermap:

- Set MAV_2_MODE = Custom
- Set COM_RC_IN_MODE = RC Transmitter Only
- Set SER_EXT2_BAUD = 500000

This Freefly video tutorial (from 5:39) explains how to set the Astro parameters.

• You can refer to the Freefly Wiki page for more detailed information on the Astro drones and Pilot Pro controller as well as Astro integration with Emesent Hovermap.

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3. Mount the Hovermap on the Freefly Astro

Emesent's Hovermap ST and Hovermap ST-X can support the Freefly Astro Max drone, while the Freefly Astro drone is supported by Hovermap ST-X.

The Astro Max has different mounts for attaching to the Hovermap ST or ST-X, and the Astro has a mount for the Hovermap ST-X:

- The different mounts are named and colour-coded so you can tell at a glance which drone and which Hovermap they belong to.
- The set up instructions shown below are the same for the Astro and Astro Max drones and Hovermap ST and Hovermap ST-X , it's just the mounts that are different.

3.1 Hovermap ST-X mount for the Freefly Astro

The Hovermap ST-X mount for the Astro is grey and unlabelled, and it has two 'arms'.



What's in the Astro interface kit

- 1. Hovermap-Astro dovetail mount for ST-X
- 2. Hovermap-Pilot Pro mode sticker
- 3. Electrical interface
- 4. USB-C dust cover
- 5. 2 x Electrical interface attachment screws (M3 x 6 2.5 mm hex drive)
- 6. 4 x Dovetail mount attachment screws (flanged 2.5 mm hex drive)

Required tool (provided)

• 2.5mm Hex Driver

3.2 Hovermap ST-X and ST mounts for the Freefly Astro Max

The Hovermap ST-X mount for the Astro Max mount is blue to match the ST-X bumpers and labelled "For ST-X only" (top image) and it has two 'arms', while the Hovermap ST mount for the Astro Max is grey and labelled "For ST only" (bottom image).



What's in the Astro Max interface kit

- 1. Hovermap-Astro Max dovetail mount for ST-X (blue) or ST (grey)
- 2. Hovermap-Pilot Pro mode sticker
- 3. Electrical interface
- 4. 2 x Electrical interface attachment screws (M3 x 6 2.5 mm hex drive)
- 5. USB-C dust cover
- 6. 4 x Dovetail mount attachment screws (flanged 2.5 mm hex drive)

Required tool (provided)

• 2.5mm Hex Driver

3.3 Installing the Hovermap-Astro Dovetail Mount

The set up instructions in this section are the same whether you're using the Astro or Astro Max drones with the Hovermap ST or ST-X – the descriptions of Hovermap, Astro and Mount are generic.

 Remove the Hovermap dovetail mount from the box and install the provided mounting screws. There will be grommets already in place. If the grommets have come loose, it may help to use an cylindrical object like the base of a pen to push the grommets into the mount.







Dovetail mounts L-R: ST-X for Astro; ST for Astro Max; ST-X for Astro Max.

2. Remove the Freefly Astro from its box and flip the aircraft. Remove the existing plastic shield from the I/O panel on the underside of the aircraft.



3. Place the Hovermap dovetail mount over the mounting holes.

Blue circles show the Hovermap ST-X mounting hole locations

Red circles show the Hovermap ST mounting hole locations

4. Make sure to align the four attachment screws with the mounting holes and screw them in using the provided 2.5mm hex driver.



The Hovermap ST-X mount on the Freefly Astro



5. Connect the Hovermap cable to the connector labelled **Payload** on the Astro, ensuring it locks into place. A clicking sound indicates the cable has been successfully attached to the aircraft.



6. Gently tuck the cables towards the rear of the Astro (directed towards the yellow connector in the payload bay), then position the plastic cover over the Astro I/O panel, making sure to leave the USB-C port accessible.





Be careful not to crush the cables between Astro and the lip of the plastic cover.



7. Place the shield back over the Astro I/O panel ensuring that it sits flush with the aircraft. Use the provided 2.5mm hex driver to secure the screws and fasten the plastic cover in place.



8. Insert the round end of the dust cover into the rubber grommet next to the USB-C port, and then connect the opposite end of the cover to the USB-C port.



9. The following image shows the I/O shield properly secured and the USB-C dust cover in place. You can now proceed to turn the aircraft upright.



3.4 Installing Hovermap on the Astro

1. Gently slide the Hovermap onto the Hovermap dovetail mount, positioning it from the front of Astro, ensuring it locks into place. A clicking sound indicates the bracket has locked into the dovetail mount.



2. Align the white dot on the electrical interface with the white dot on the port on the Hovermap. Press firmly to connect the electrical interface, making sure it locks into place. A clicking sound indicates the cable has been successfully attached to the Hovermap.





3. Test the cable connection by gently tugging on the cable to ensure it is positively retained on the Hovermap.



If the cable fails to keep connected during this test, it is recommended to get in touch with Emesent support.

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3.5 Placing the Hovermap Mode Sticker on the Pilot Pro Controller

Follow these steps to install the custom sticker label for switch modes on the Freefly Pilot Pro controller. This sticker is included in the Hovermap-Astro Interface Kit.

1. Locate the S2 toggle switch in the upper-right area of the Freefly Pilot Pro controller.



2. Peel the sticker from its backing sheet and place it as shown below.



4. Install Emesent Commander on the Freefly Pilot Pro controller

Emesent Commander can be installed either from an external storage device or via the Freefly updater app. If you do not have the latest version of the Commander .apk file on external storage, skip to the Install Commander with the Freefly Updater App section below.

When using Astro or Astro Max, if you enable the FPV feed via Commander settings while the Freefly Auterion software platform is being run, it may result in FPV feed stuttering. For that reason, when Commander detects a Freefly Astro or Astro Max, the FPV feed is hidden by default and the point cloud is displayed in the Main View. The FPV feed can be manually enabled in Commander settings when Auterion is closed.

4.1 Installing via External USB storage

A If you don't have the latest Commander version installed, you will first need to uninstall the earlier version.

- 1. Go to the Emesent Software Downloads page.
- 2. Download the software application package to your external USB storage device.
- 3. Press the power button on the Pilot Pro twice to turn on the controller and the tablet (with the current Freefly firmware). This will power on both the tablet and the controller.
- 4. Connect the external storage device containing the downloaded .apk file to one of the USB-C ports on the controller.



- 5. Copy the APK file to the Pilot Pro tablet.
- 6. Open the **My Files** app on your tablet then go to the **Internal storage** section to access the external USB device that contains the APK file.



7. Locate and tap on the .apk file then tap **Install** to begin.



- 8. Follow the installation steps. If necessary, grant the file browser permission to install apps.
- 9. Wait for the installation to complete.



4.2 Install Commander with the Freefly Updater App

- 1. Hold the power button on the Pilot Pro tablet for four seconds. This will power on both the tablet and the controller. Press again when prompted on the controller to complete powering on.
- 2. Enable Wi-Fi on the tablet and connect to a nearby wireless network or hotspot that has internet access.



- 3. Open the Freefly Updater app.
- 4. Tap the **Settings** icon then go to the **Repositories** menu.

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Manage installed apps	
Repositories Add additional sources of apps 2	
Updates	
Over Wi-Fi Always use this connection when available	
Over data	•
Automatically fetch updates	
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- 5. Tap **New Repository** on the top right.
- 6. In the repository address, enter the following address and click **ADD**: http://freefly-updater.freeflysystems.com/v1_third_party/emesent/stable_repo/



• The above address begins with **http://** not **https://** - you will need to clear out the pre-entered text entirely and enter the one above.

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7. Once the new repository has been added, it is marked as "Unsigned" in red. Ignore this and continue with the installation process. Make sure the toggle for the repository is enabled.

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8. Tap the back arrow and go to the **Latest** menu. Pull down to refresh the list of apps.



- 9. Tap the Commander app entry to open it then tap **Install**.
- 10. Follow the installation steps and wait for the process to complete.



4.3 Disabling USBHID Mode

This step is not necessary if you have Commander 2.0 as a minimum.

To prevent Emesent Commander from being minimized when using the Hovermap switch (S2) on the Pilot Pro controller, follow these steps:

1. Open the **Pilot Pro** app.



2. Tap the Hamburger button the select **Advanced**.

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3. Set **UsbHidMode** to **0** (zero) then tap **Submit**.

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5. Setup Hovermap and Freefly Astro for basic operations

The instructions in this section are the same whether you're using the Astro or Astro Max drones and the Hovermap ST or ST-X, and the descriptions of Hovermap, Astro and Mount are generic.

5.1 **Powering on the Hovermap**

- 1. Press the power button on the Pilot Pro twice to turn on the controller and the tablet (with the current Freefly firmware).
- 2. Power on the Astro. See the section below Powering on the Astro.
- 3. Power on the Hovermap

You can configure Hovermap through the Web UI to power on automatically as soon as power is supplied.

4. Wait as the Hovermap cycles through several stages. The status LEDs at the back of the Hovermap will flash red for approximately 30 seconds as the system boots. Hovermap is ready when the status LEDs show a breathing blue pattern, which can take about 60 seconds.

5.2 Setting the Pilot Pro to Hovermap Mode

1. Set **Switch 2 (S2)** on the Pilot Pro controller to **Hovermap/Offboard** mode (highest position away from the pilot).



2. Check that the status screen shows **Position** or **Pending**.

The status will change to **Offboard** once the Astro is armed.

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5.3 Connecting to the Hovermap

Emesent Commander communicates directly with the Hovermap via the Freefly Pilot Pro controller. Connection to the Hovermap's Wi-Fi network is not required.

- 1. Ensure Hovermap is powered and ready.
- 2. Turn off the Wi-Fi on the Pilot Pro tablet.



As stated above, communication with the Hovermap is done via the controller. The Wi-Fi on the Pilot Pro tablet <u>MUST BE DISABLED</u>.

- 3. Launch Emesent Commander then tap **Connect** at the top of the landing page.
- 4. On the page that displays, set Hostname/IP address to 192.168.144.101.
- 5. Tap the **Tick** icon then tap **Close**.
- 6. Once the connection is established, you will hear an audio message indicating that you are "Connected" and the mission tiles are enabled.

• Due to interference caused by the Pilot Pro controller to nearby Wi-Fi connections, the Observer Mode feature is only available via an Ethernet connection when using the Freefly Astro. For more information on using the Observer Mode, refer to the Hovermap user manual.

5.4 Initial Hovermap and Astro Setup for Assisted or Autonomous Missions

- 1. Now the Hovermap is powered and a connection is established, select the tile: **Assisted or Autonomous Mission**.
- 2. Progress through the mission workflow until you reach the **Scan setup** page.
- 3. Start a scan to allow Hovermap to initialize settings on Astro.

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	an audio alert consisting of three beeps. This will only need t	o be performed on the
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Mission workflow	SCAN SETUP
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🥪 Pre-mission settings	🤣 Communications ready 🔺
Scan setup	Set scan name and start
	ST5232AstroRc4Enogge
	Storage 485.568 (90.9%) used
	STOP SCAN
	Mission name: ST5232AstroRc4Enogge_02
	Pre-scan check status
The robot requires restart before pre-mission checks can be completed.	Pre-scan checks failed
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- 4. Turn off the Astro.
- 5. Repeat the steps in this guide you have just performed, from **Powering on the Hovermap** back to step 2 above: Progress through the mission workflow.
- 6. Start a scan.
- 7. Wait until pre-mission checks have passed you'll hear the "**Hovermap Ready**" alert sound indicating you are ready to fly.
- 8. Then select **Continue to progress to the main screen** and you are ready to fly.

5.5 Powering on the Astro

1. Extend the arms of the Freefly Astro to allow you to access the battery bays. Each arm must be extended and locked into place.



- 2. Place both batteries on top of the Freefly Astro and slide them into place. Firmly press to ensure proper connection. Each battery will make two clicks when installed.
 - The Freefly Astro will not arm if only one battery is installed.



3. Press the power button on either of the batteries twice to power the aircraft.



4. The battery display should read "Hotswap" after the second press.



5. The second battery automatically powers up (and also shows "Hotswap" on the display) when the first battery is turned on. The green and red LEDs should light up at the end of the aircraft arms.



If Freefly Astro motors (or batteries) become too hot, the Astro will enter one of two warning states. First, a warning will be displayed in Auterion – Freefly recommend moving the Astro around slowly to get airflow into the motors. If the warning is critical, the boom LEDs will flash – Freefly recommend landing the Astro immediately. 8

5.6 Arming the Freefly Astro

1. Push the left control stick downwards and towards the center of the controller for three seconds.

For safety reasons, the Astro will disarm 10 seconds after arming if no input is detected.

2. Wait until the status LEDs at the end of each arm of the Astro increase in brightness and the motors start to spin. The status screen on the Freefly Pilot Pro changes from **Position** or **Pending** to **Offboard**. This indicates that the Hovermap has control of the Freefly Astro and they're ready to fly.



To learn more about Hovermap operations, please refer to the Hovermap user manual.

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5.7 Disarming the Freefly Astro

- 1. Hold the throttle down for two seconds.
- 2. Wait until the status LEDs at the end of each arm dim and the motors stop.

5.8 **Powering down the Freefly Astro and Hovermap**

- 1. Hold down the power button on either of the batteries for approximately 5 seconds
- 2. Wait until **Entering Standby** is shown on the battery status screen.
- 3. The Hovermap will automatically shut off when the Freefly Astro is powered down.



5.9 Powering Down the Pilot Pro Controller

Holding down and the releasing the power button (a long press) will power down the Pilot Pro and the tablet together.



5.10 Recovering Astro flight logs

If your Freefly Astro or Astro Max aircraft has been involved in a hazardous incident or displayed unexpected flight behavior, please report the incident to us and share your flight log files through the Customer Support form online.

If the aircraft is registered in the Auterion Suite, Astro will automatically upload flight log files to the Suite when a WiFi or LTE connection is available.

The flight log files are stored to the onboard SD card and can be downloaded to a PC. You can access the Freefly flight logs using a USB connection between the tablet and the remote control.

For instructions to recover flight logs from your Freefly Astro or Astro Max, refer to the Pilot's Operating Handbook section on Auterion Suite / Flight Logs.

5.11 Resetting the Astro

If the Hovermap is disconnected from the Astro, reset the aircraft to its default parameters.

- 1. Open Auterion Mission Control (AMC).
- 2. Activate **Advanced Mode** by tapping the AMC icon six times and confirming at the pop-up screen.

The icon will change to an outline when **Advanced Mode** is active.

3. Connect AMC to the Astro.

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- 4. Go to Vehicle setup > Parameters > Tools then tap Reset to vehicle's configuration defaults.
- 5. After resetting, go to **Vehicle setup > Parameters > Tools** then tap **Reboot Vehicle**.
- 6. Calibrate sensors as required.



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